

#### Outline

- Background of embedded intelligence
  - Autonomous cooperation
  - Hardware layers
  - Communication as limiting factor
- Case studies and examples
  - The intelligent container
  - Local route planning

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Intelligent RFID + Business case

Autonomous control means that intelligent objects make decisions on their own. Parcels, vehicles or transport orders are represented by individual software programs or agents.

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#### Intelligent objects

None

Maximum

freedom

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- Each object is equipped with a certain Degree of decision freedom
  - Executes decisions of central server
    - Observes its environment
    - Change transport route
    - Swap vehicle by own decision
    - Changes its destination, according to new orders or changed quality state

#### **Object representation**

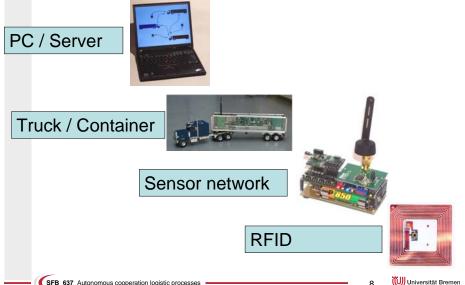
- Agent physically linked to object
  - Object / parcel has own computation unit
- Agent represents object
  - Agents runs remote on server platform to act 'in behalf' of the object

2

Various system layers can provide a platform for embedded intelligence. The costs for additional computation power are low in relation to the basic hardware costs

## **Hardware Layers**

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#### Limiting factors of communication

- Passive RFID:
  - Access only offline during gate passage
  - Limited range (~3 m)
- Active wireless sensor:

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- Permanent online access and higher range
- But volume limited by energy budget
- Thinking is cheaper than communication
  - Sending one message ⇔ 3 Seconds CPU at full speed

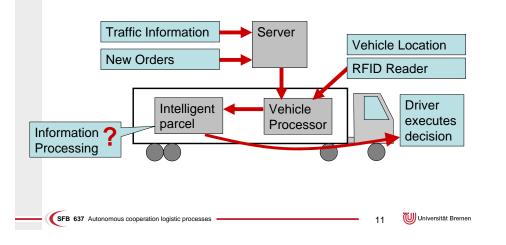
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Local data possessing extends battery life time by reduces communication

Information should be sent over the shortest path from source to sink. Implementing the decision system on the 'wrong' hardware layer could even increase the communication volume.

## The example of the intelligent parcel

- Length of the information path
  - Source  $\rightarrow$  Processing  $\rightarrow$  Sink



## Length of the information path

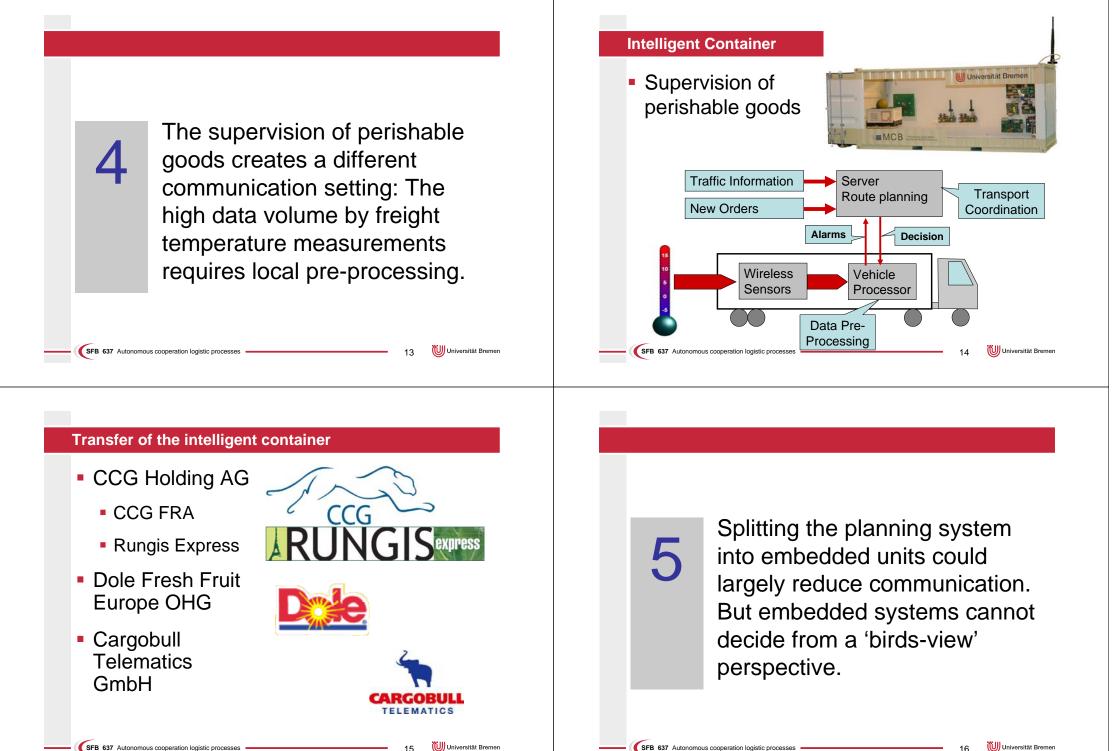
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- Keep it as short as possible
  - Length depends on location of the processing
- Processing close to origin of information
  - Route decision ~ 100 Byte

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Sensor supervision ~ 10 kByte

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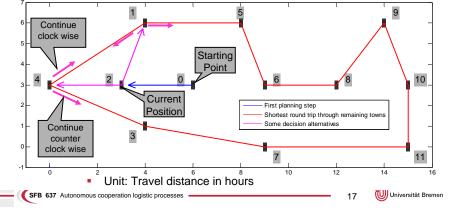


15

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#### Splitting the route planning process

- Example: Truck autonomously adapts a round trip to deliver sensitive parcels to multiple costumers
- Split Planning: Remote server suggests round trip, truck decides to go clockwise or count clockwise and where to start



## Performance of different planning strategies

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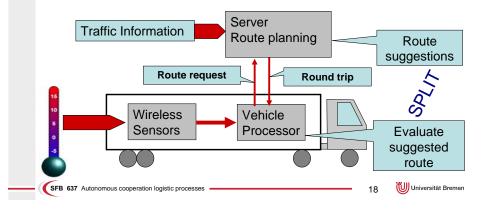
- How good is planning under this restriction?
- Vehicles start with optimal route, but disturbance and replanning after 2 packages
- 500 software experiments with N<sub>0</sub> = 20 packages to deliver

Method	Delivered Packages	Driving time	Improvement
Full re-planning ( <b>Bird view</b> )	16.41	76.81 hours	100 %
Vehicle planning (Local view)	15.66	76.82 hours	64.5 %
Repeated vehicle planning	15.75	75.80 hours	68.6 %
Unchanged route	14.30	74.68 hours	0 %

#### Local Route Planning

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- Reduced information: Vehicle receives only a limited number of route suggestions
- Truck evaluates the suggestions by internal quality information
  - Deliver packages with low remaining shelf life first
  - Maximize the number of deliveries in proper quality state



Automated evaluation of temperature charts is even feasible inside the hardware of semi-passive RFID labels.

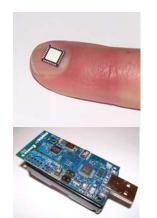
#### The idea of intelligent RFID Shelf life modeling Calculation of Sensor data pre-processing by semiloss per day as function of Tomato Green Q0(15°C)=14.95 passive RFID tags Tomato Red Q0(15°C)=8.77 temperature Tomato Pink Q0(15°C)=13.83 Q0(15°C)=23.45 Papaya Arrhenius Only state flag transmitted at Temperature Function to access Q0(15°C)=3.29 Loss per Day Beans equation for measurement effects of temperature read out reaction onto quality kinetics Look up table Shelf Life (days) 12 15 20 25 Temperature in °C WAGENINGEN UNIVERSITY HORT BUIENCES SFB 637 Autonomous cooperation logistic processes SFB 637 Autonomous cooperation logistic processes Universität Bremen Universität Bremen 22 21

## **Required hardware resources**

Is it feasible to squeeze a shelf life model into a micro-chip?

Type of Resource	Calculation of Arrhenius equations
Processing time	1.02 ms
Program memory	868 bytes
RAM memory	58 bytes
Energy	6 µJoule

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23

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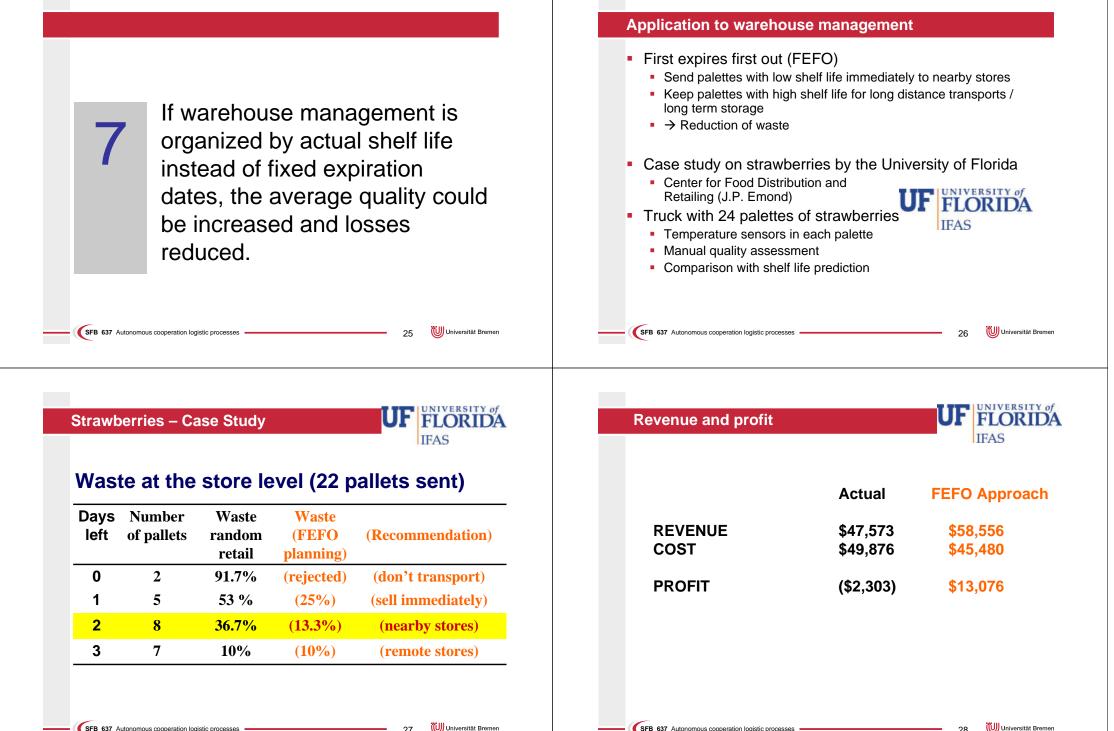
#### Available energy

- Very small additional recourses compared to circuit of data logger
- Shelf life model can run by paper thin batteries
- Finished project: HF-Tag for Measurement of pressure

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Power consumption per month			
Update every 15 minutes	0.020 J / month		
Stand by current of MSP430	5.7 J / month		
(1µA at 2.2V)			
Turbo Tag (Zink oxide battery)	80 J		





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#### Summary

- Benefits of embedded intelligence
  - Large reduction of communication costs
  - Only few extra hardware costs for additional processing power
  - Increased robustness and flexibility
  - Not all hardware levels are useful
  - Length of the communication path

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# Thank you for your attention

For more information and publications please visit www.intelligentcontainer.com

Contact address
 Dipl.-Ing. Reiner Jedermann
 Universität Bremen, FB1 (IMSAS), Otto-Hahn-Allee NW1,
 D-28359 Bremen, GERMANY
 Phone +49 421 218 4908, Fax +49 421 218 4774
 rjedermann@imsas.uni-bremen.de

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29

30 Universität Bremen